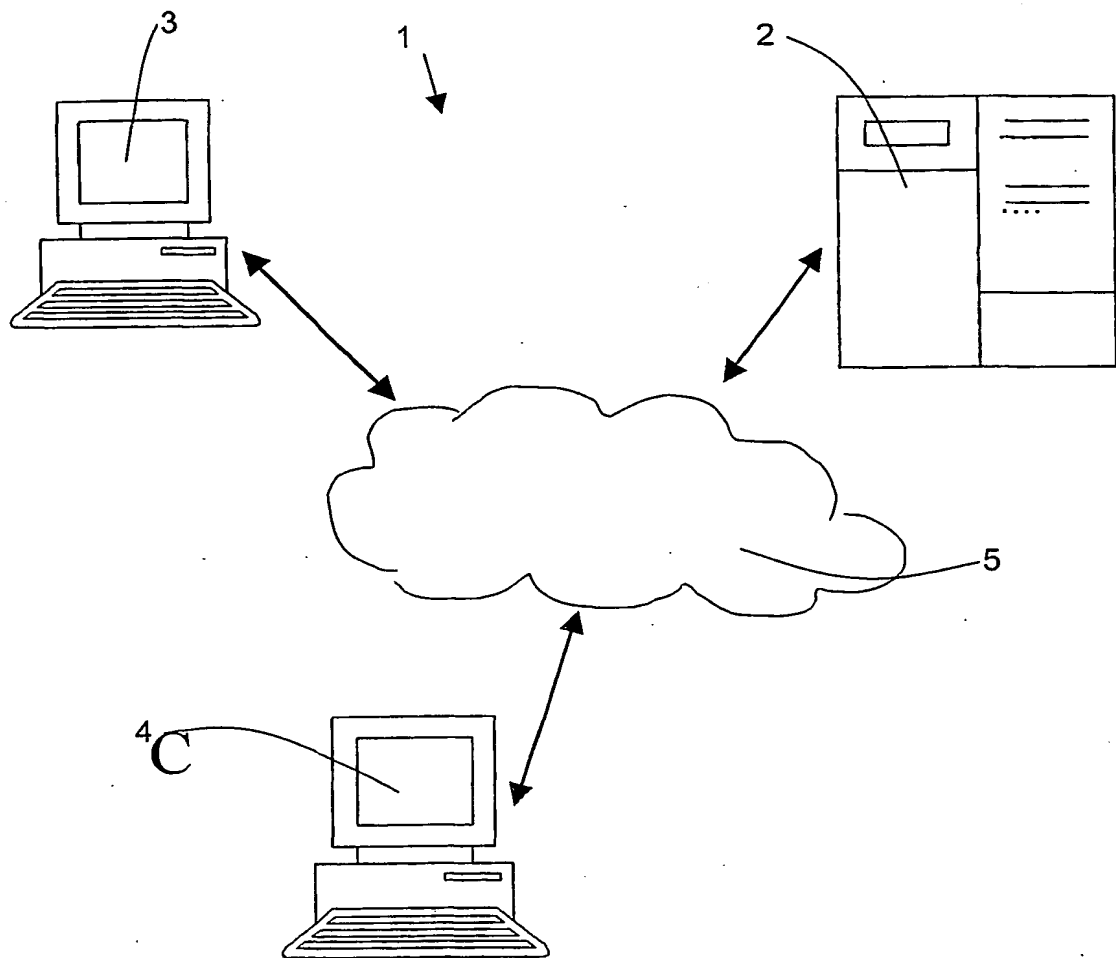
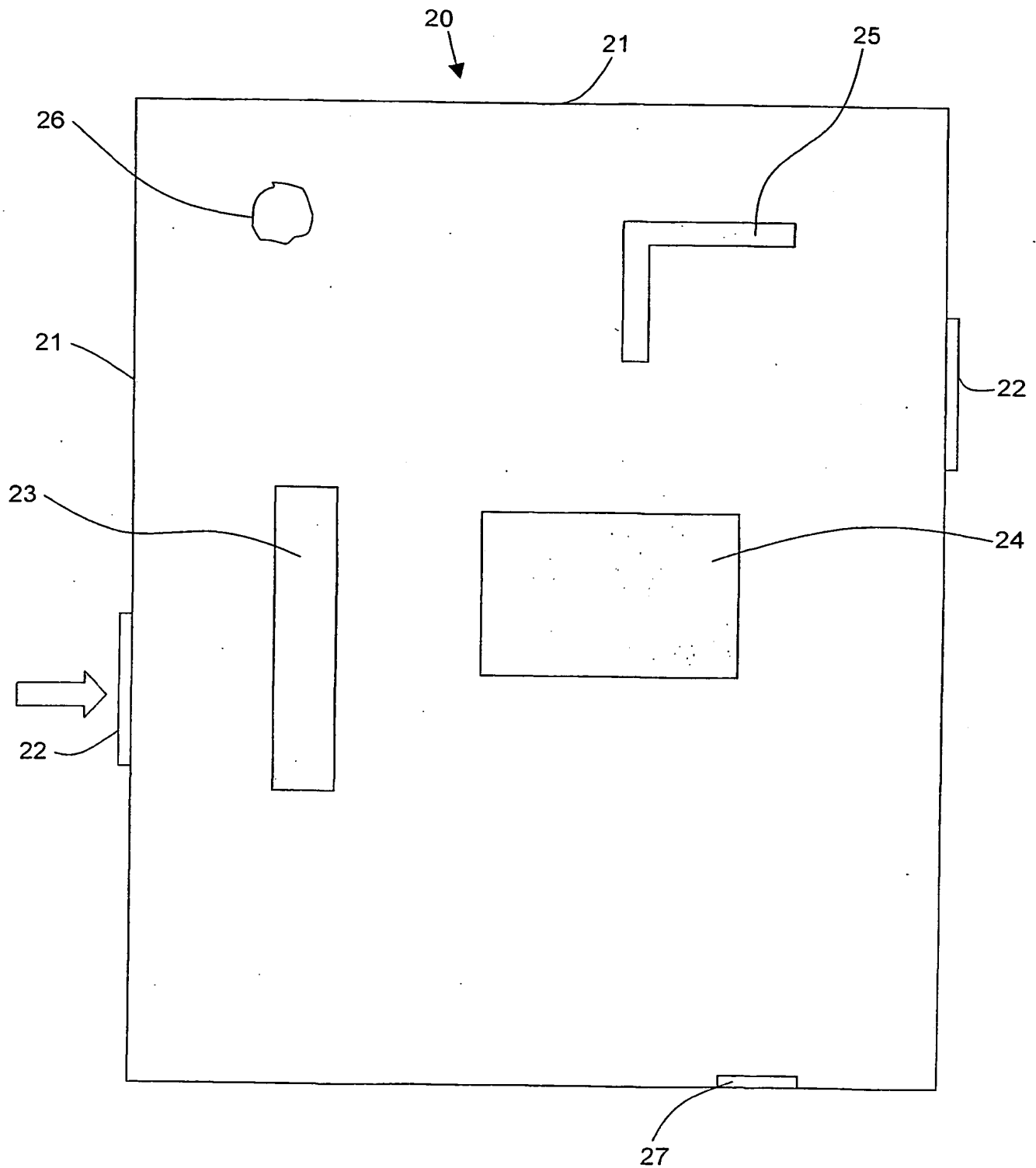


1/17

Figure 1

2/17

Figure 2

3/17

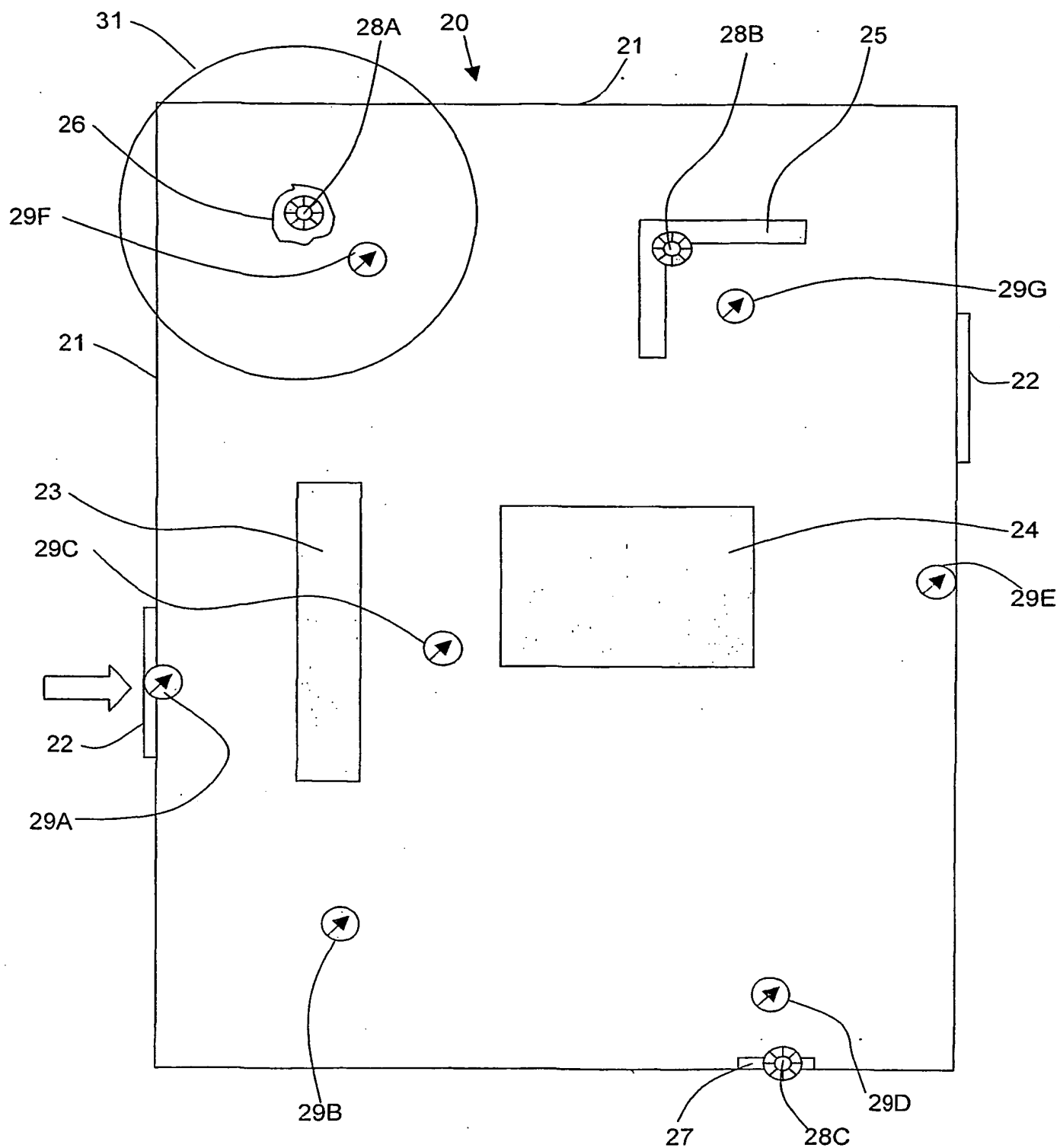
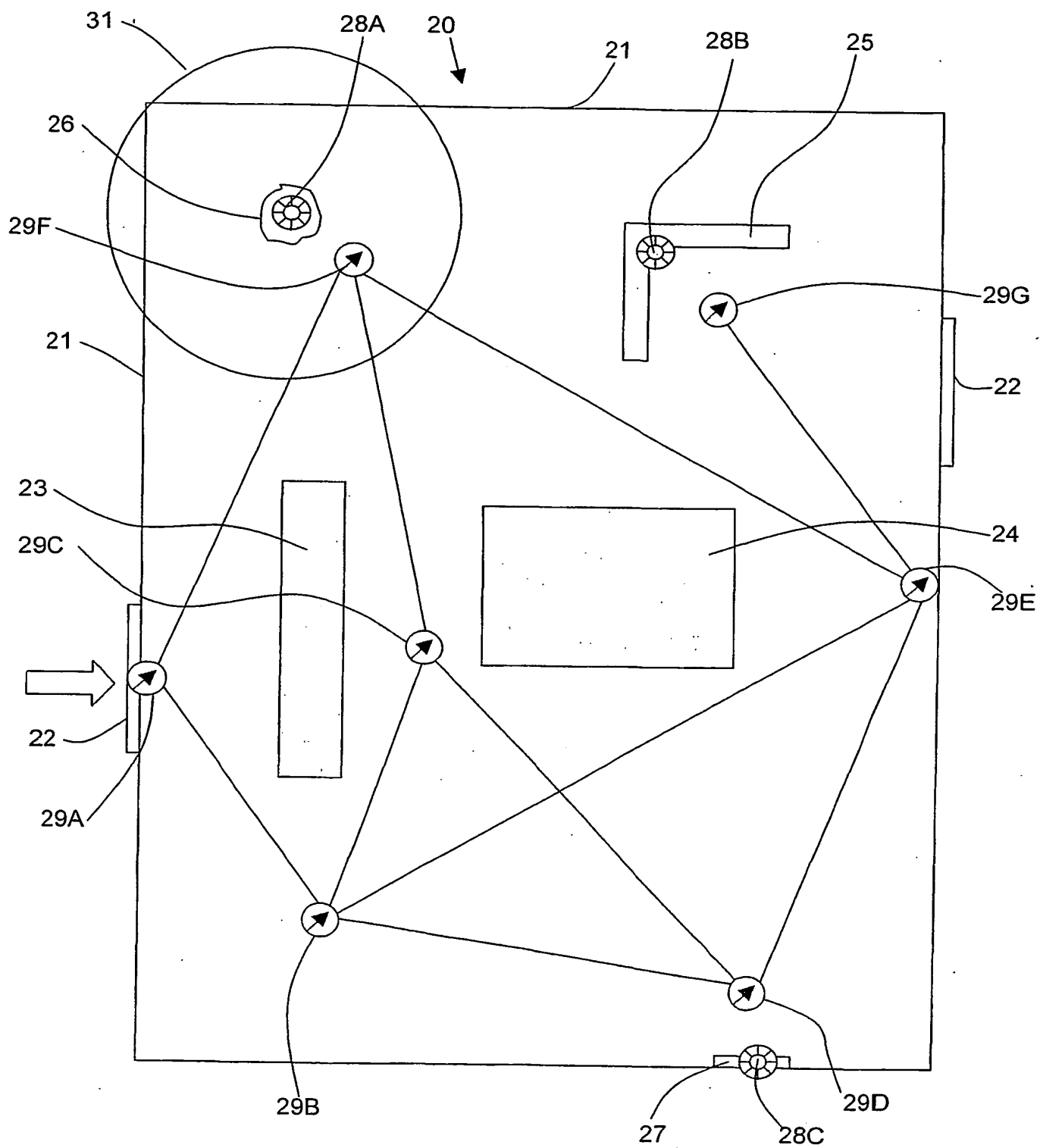
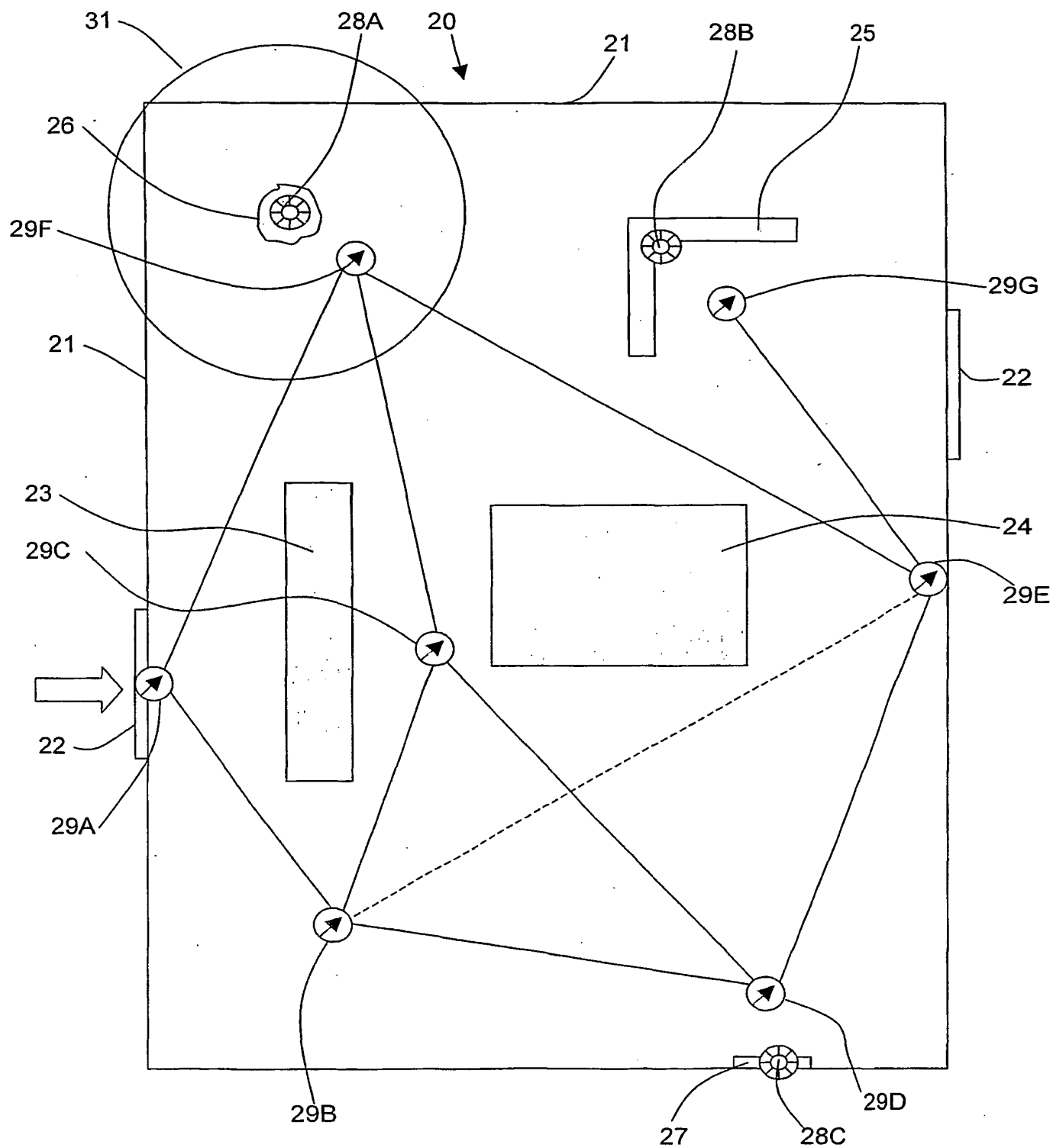
Figure 3

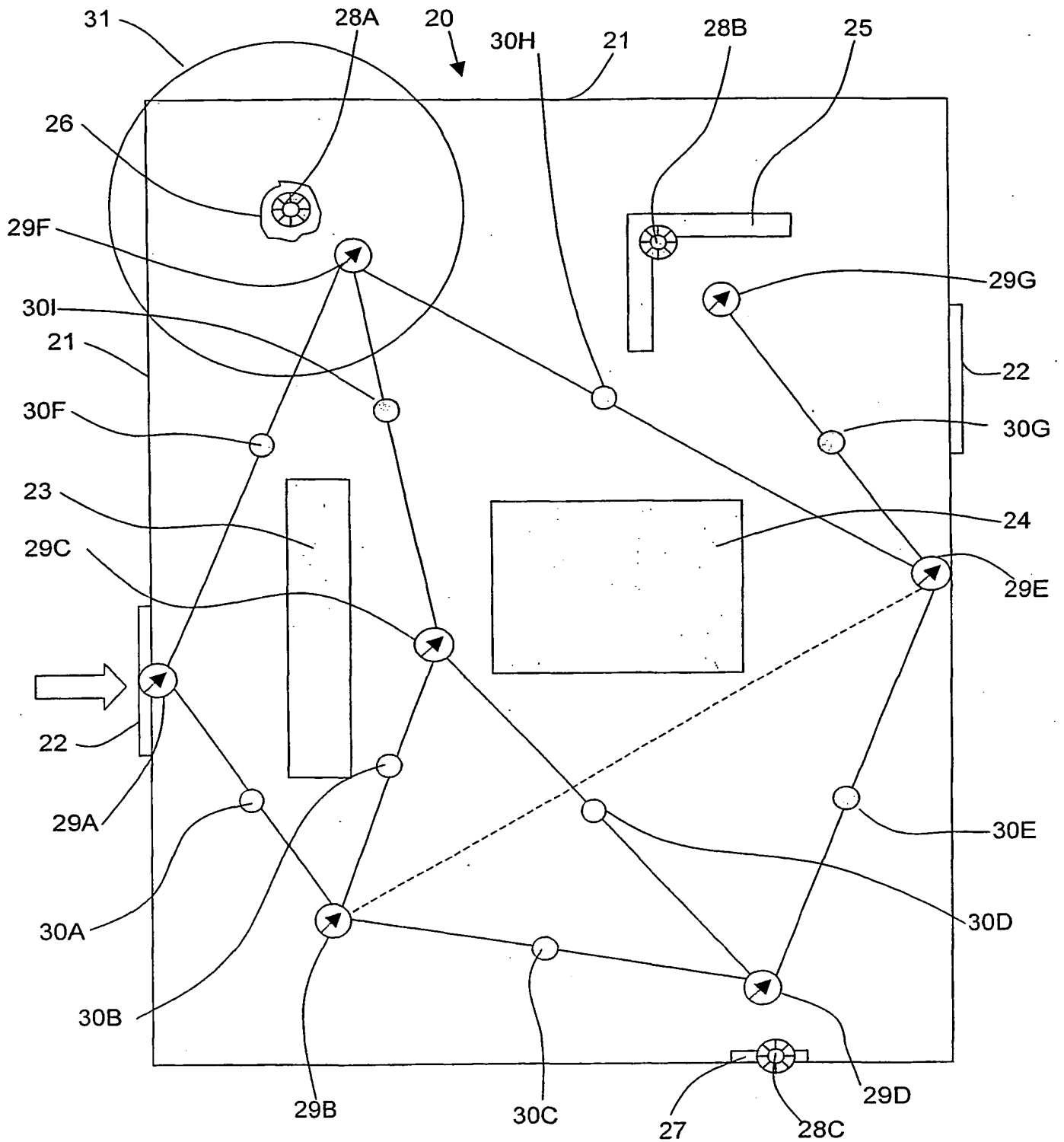
Figure 4



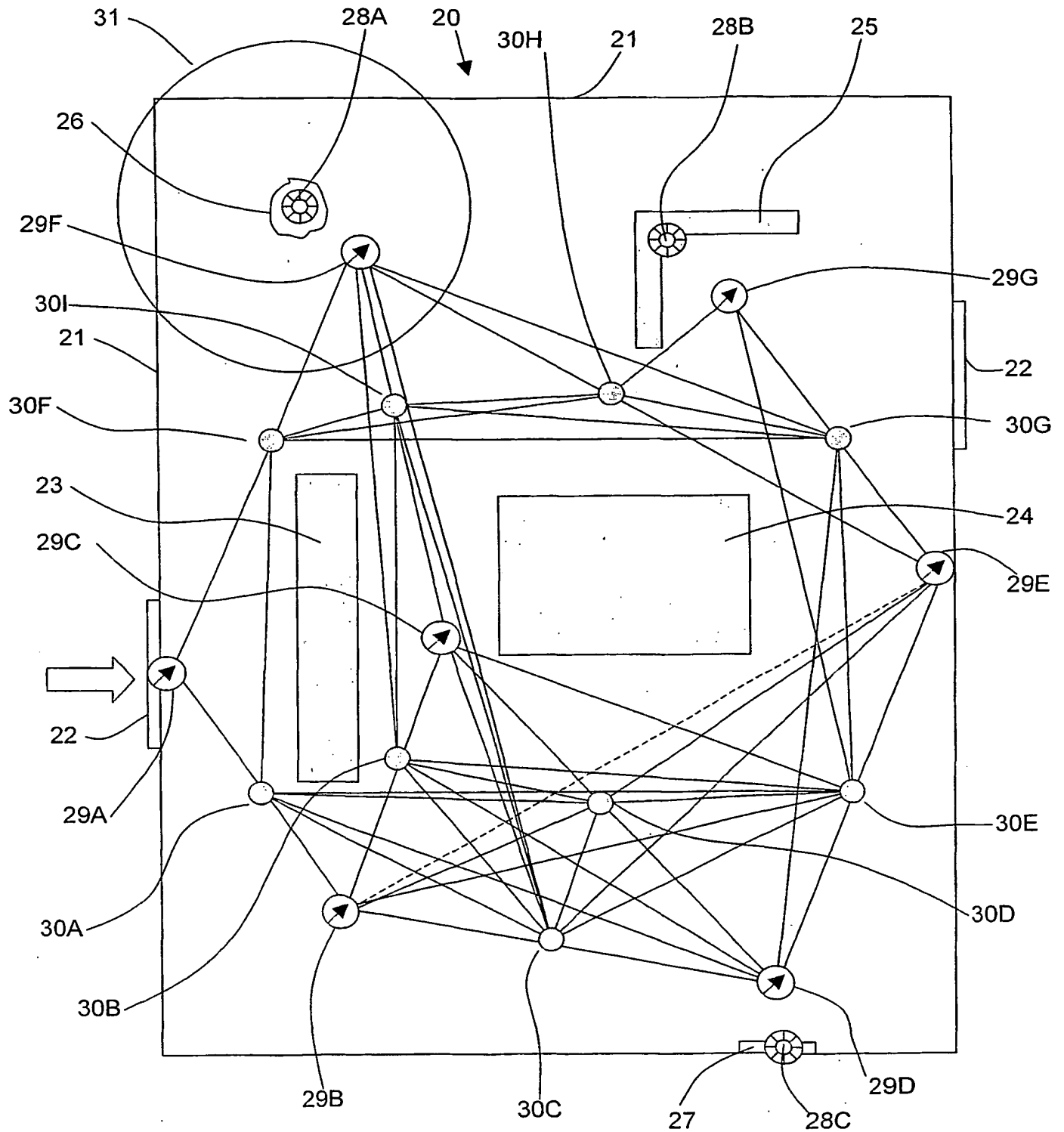
5/17

Figure 5

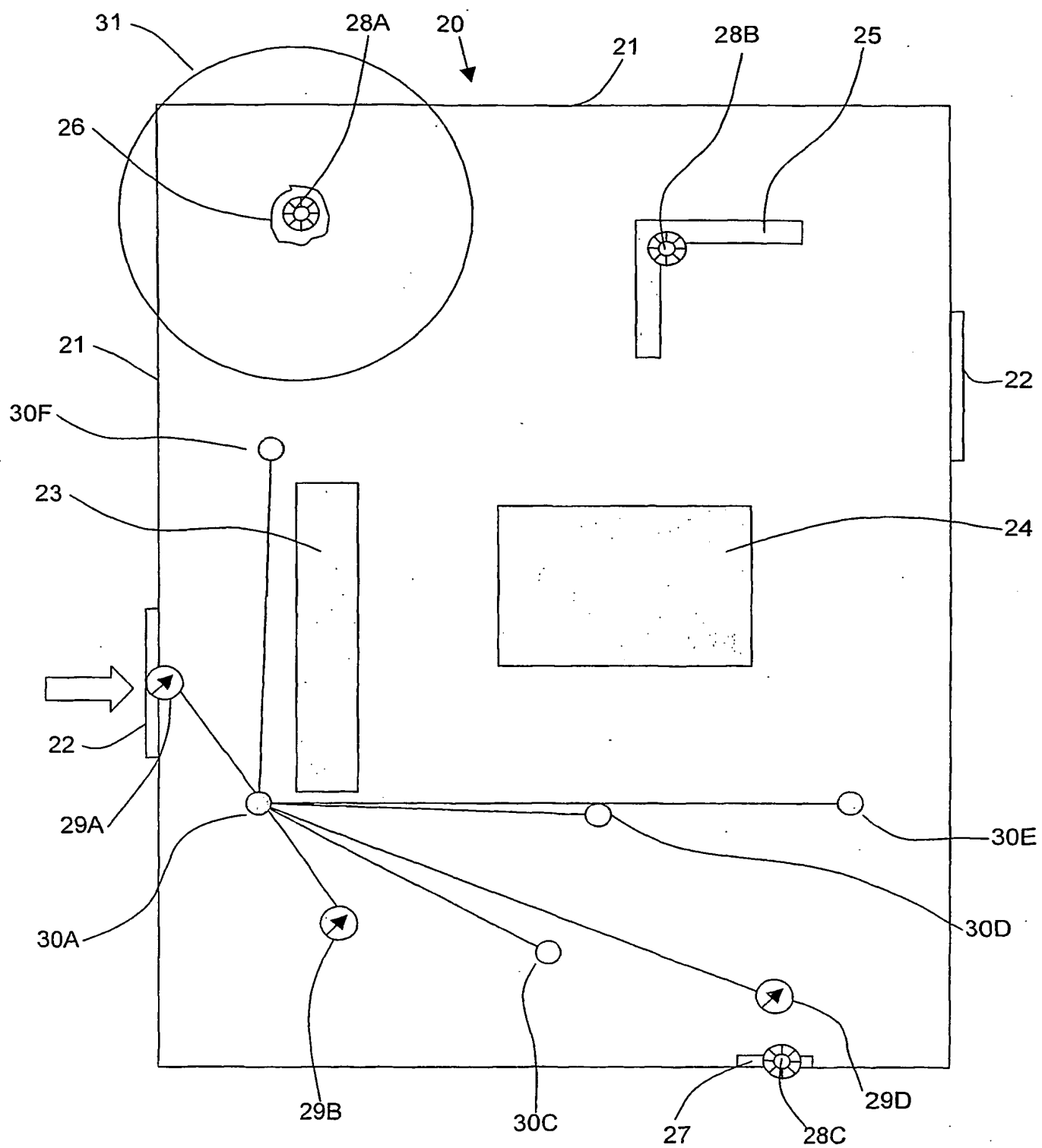
6/17

Figure 6

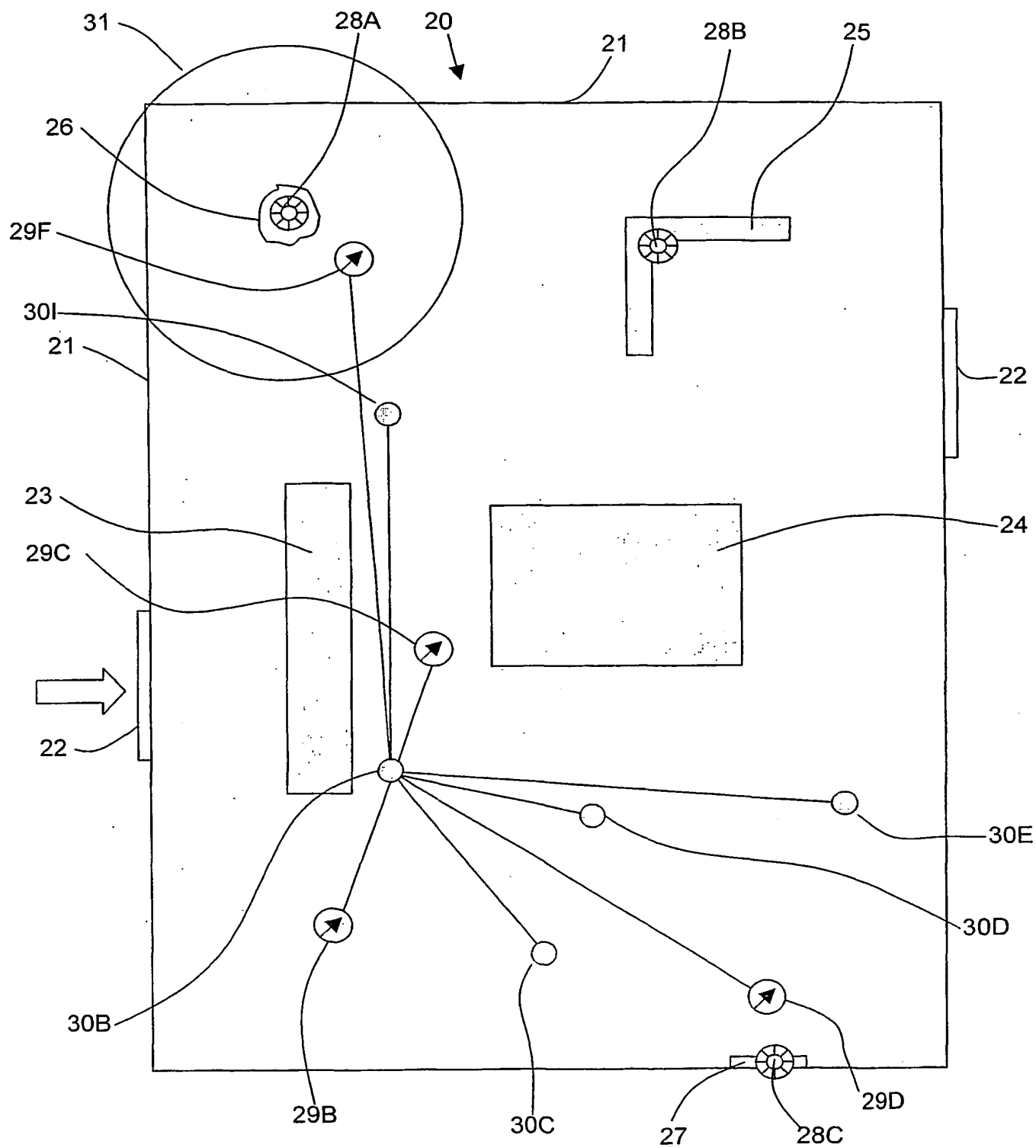
7/17

Figure 7

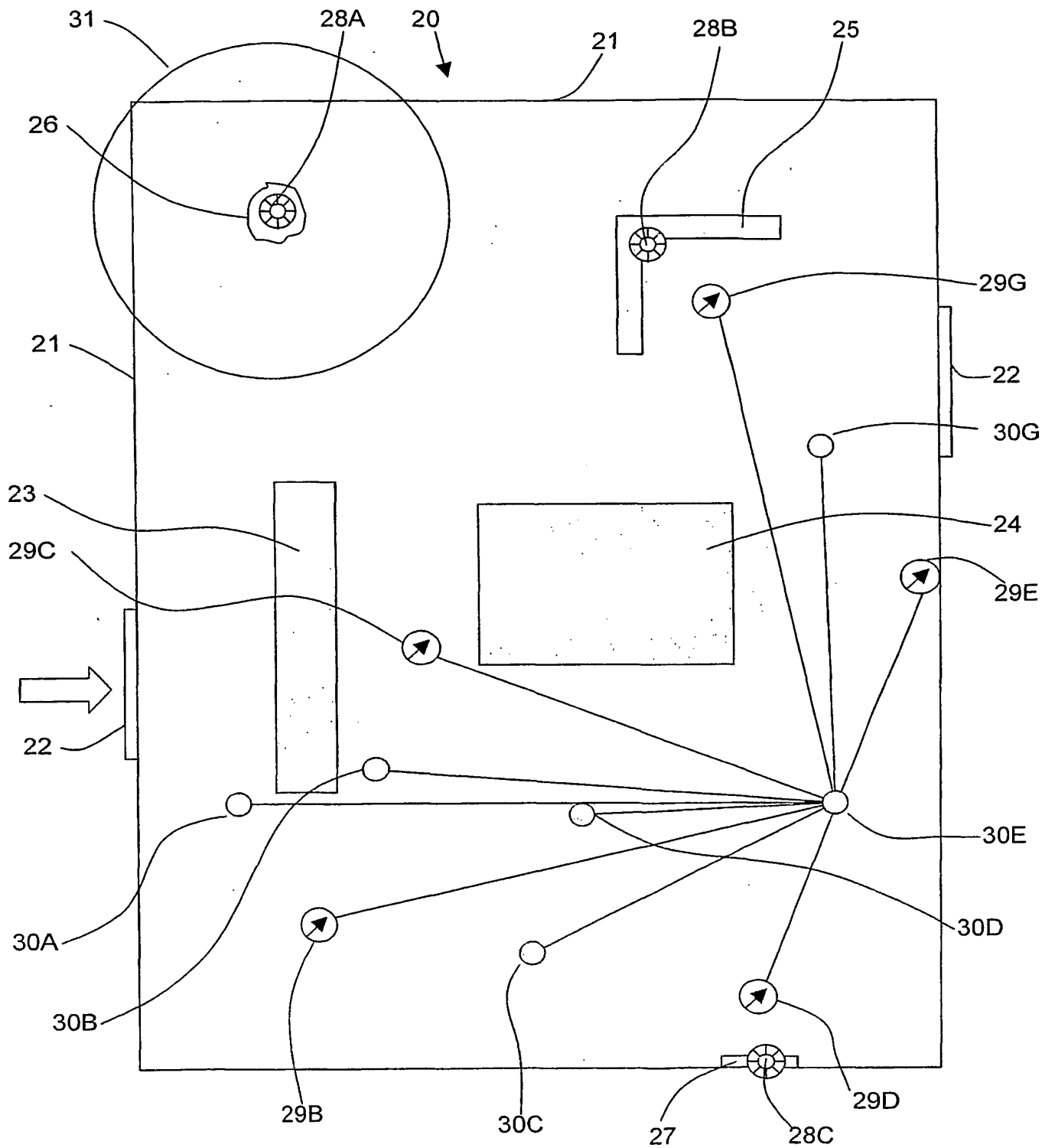
8/17

Figure 8

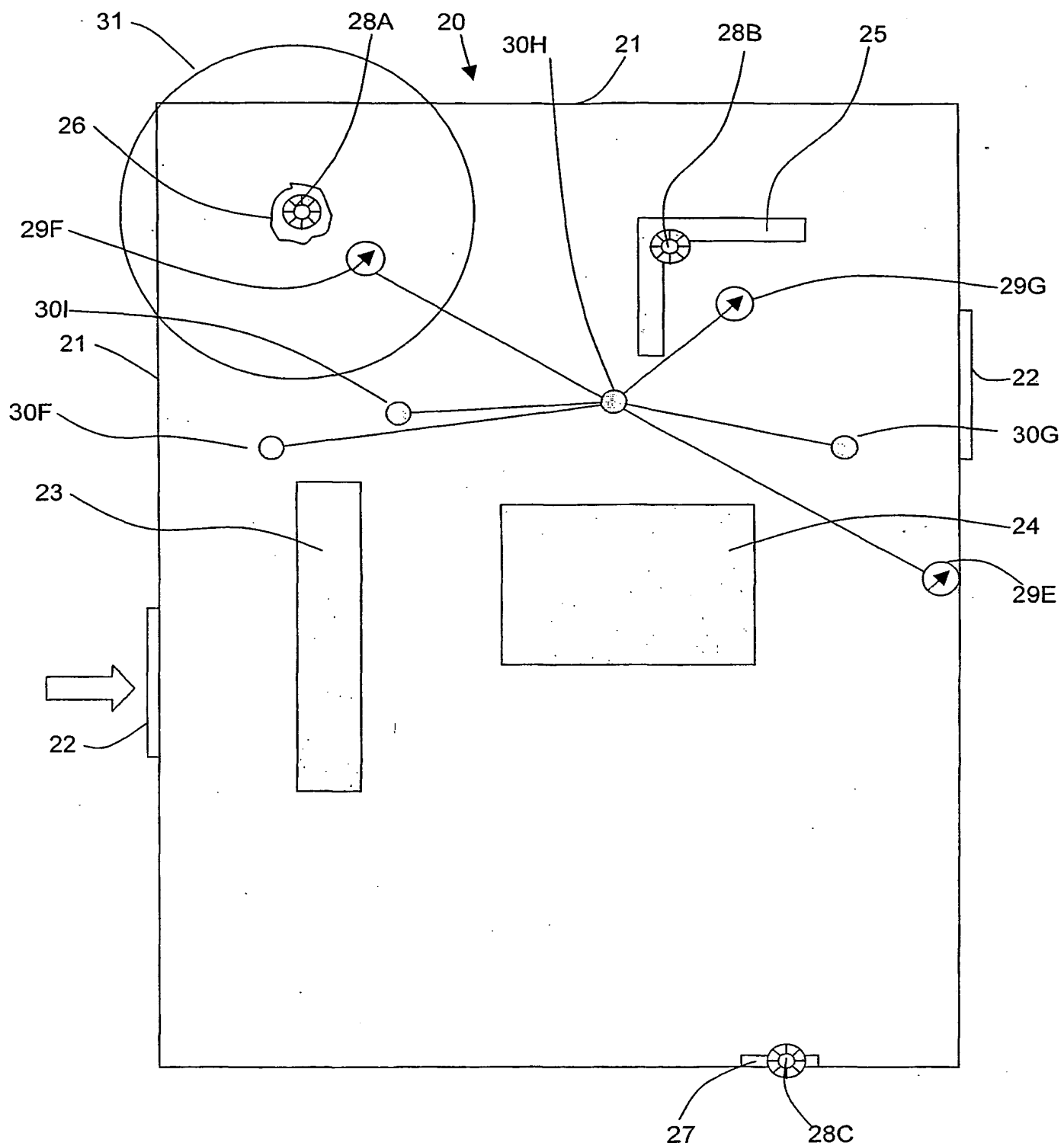
9/17

Figure 9

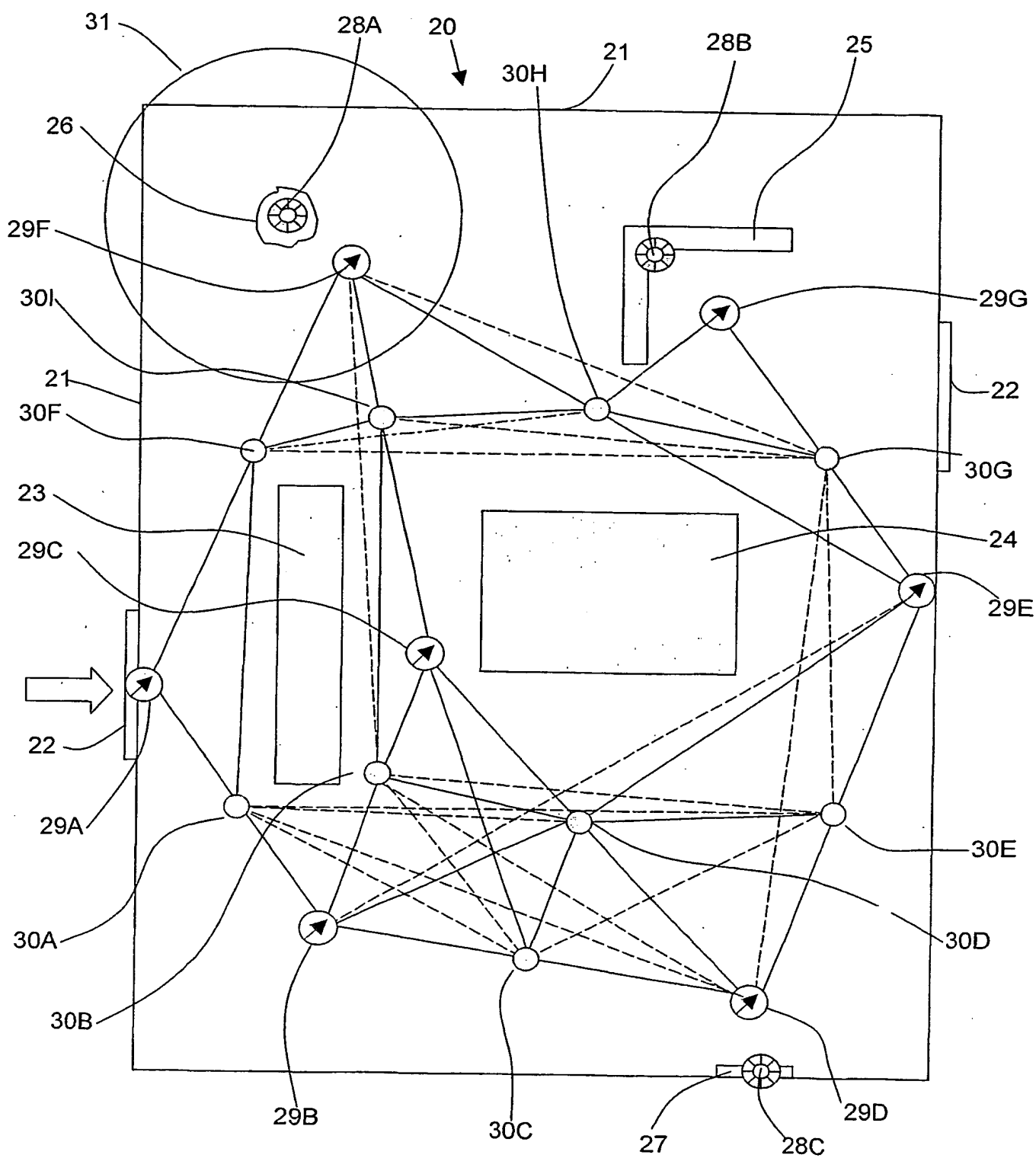
10/17

Figure 10

11/17

Figure 11

12/17

Figure 12

13/17

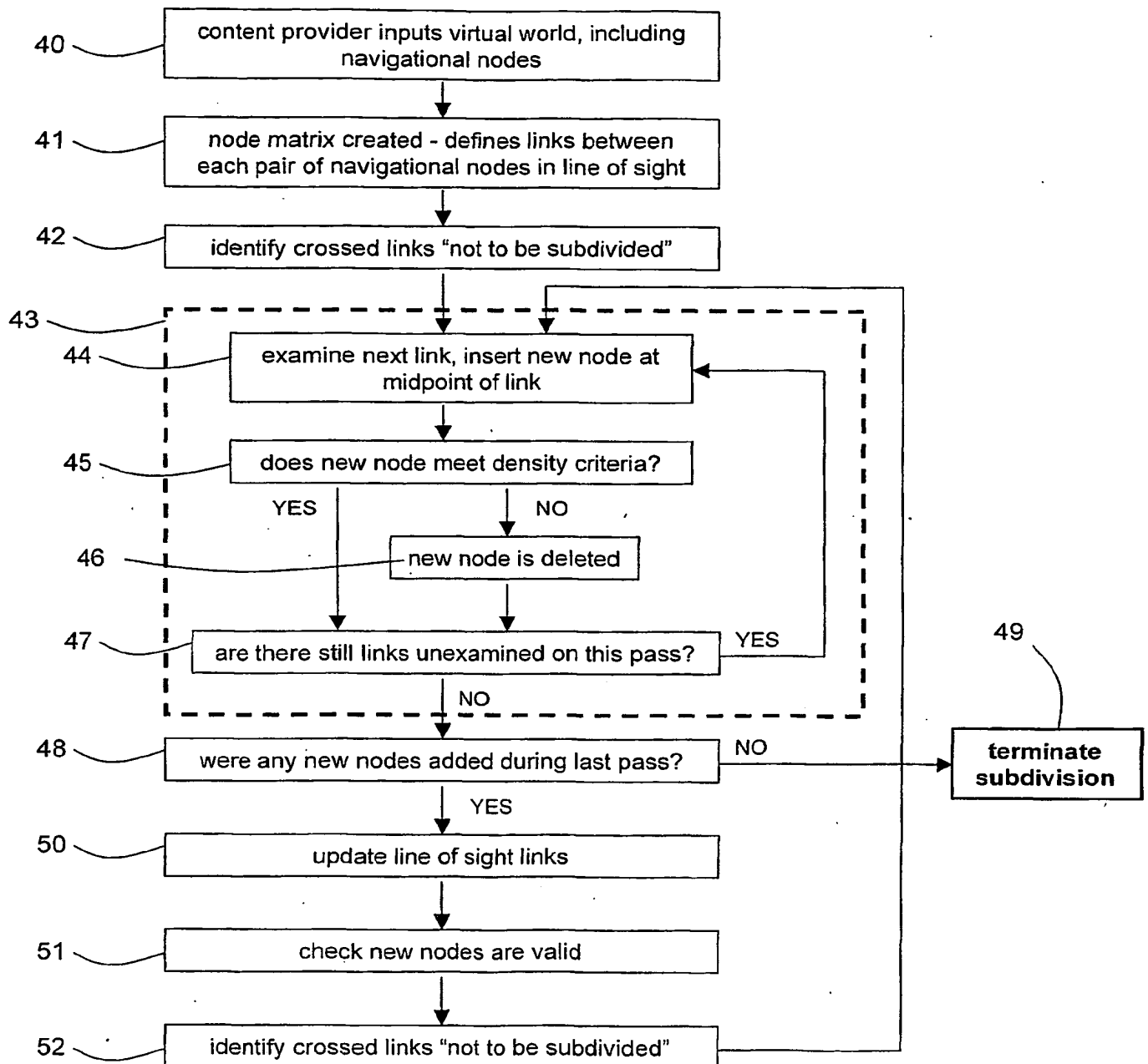
Figure 13

FIGURE 14A

OPTIMUM NODE
CONNECTION

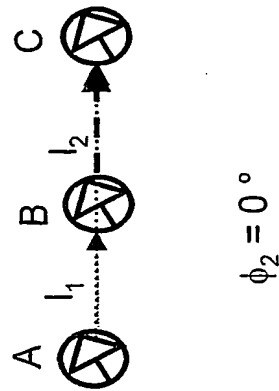


FIGURE 14B

AVAILABLE NODE
CONNECTION

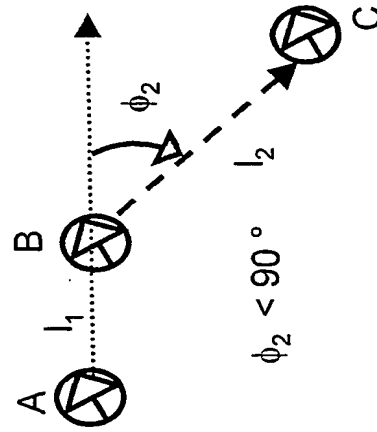
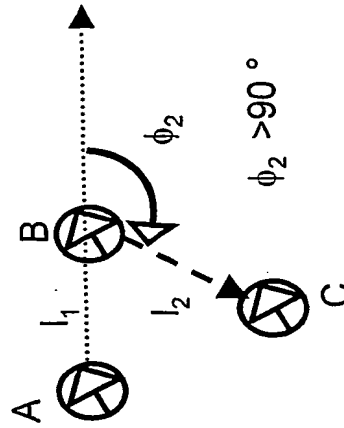


FIGURE 14C

INEFFICIENT NODE
CONNECTION

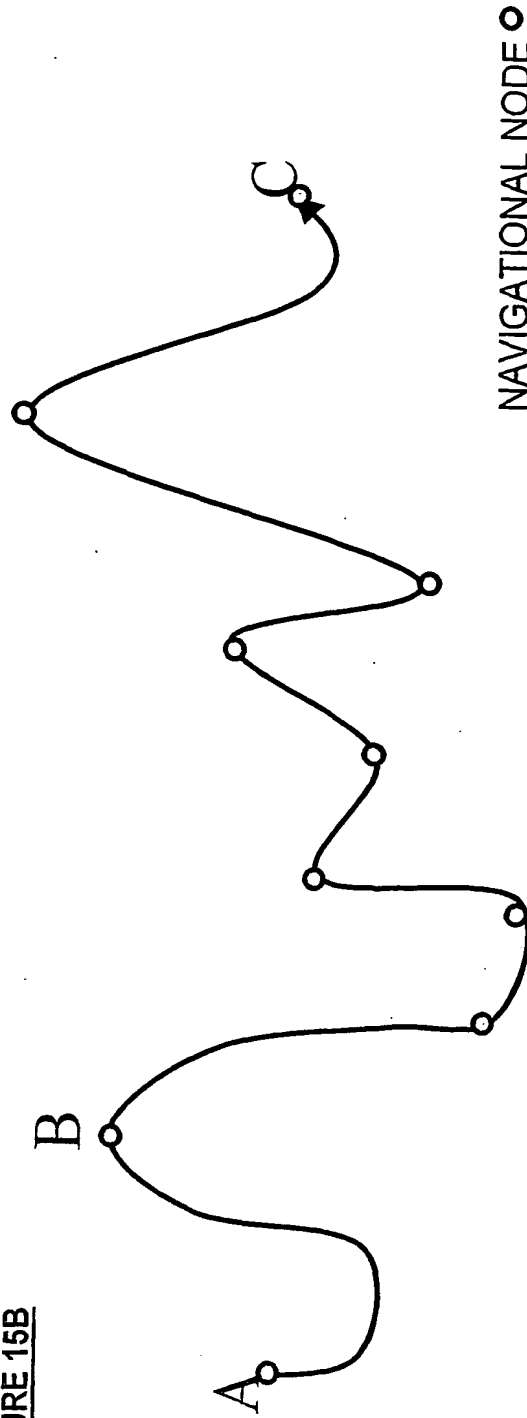


15/17

FIGURE 15A



FIGURE 15B



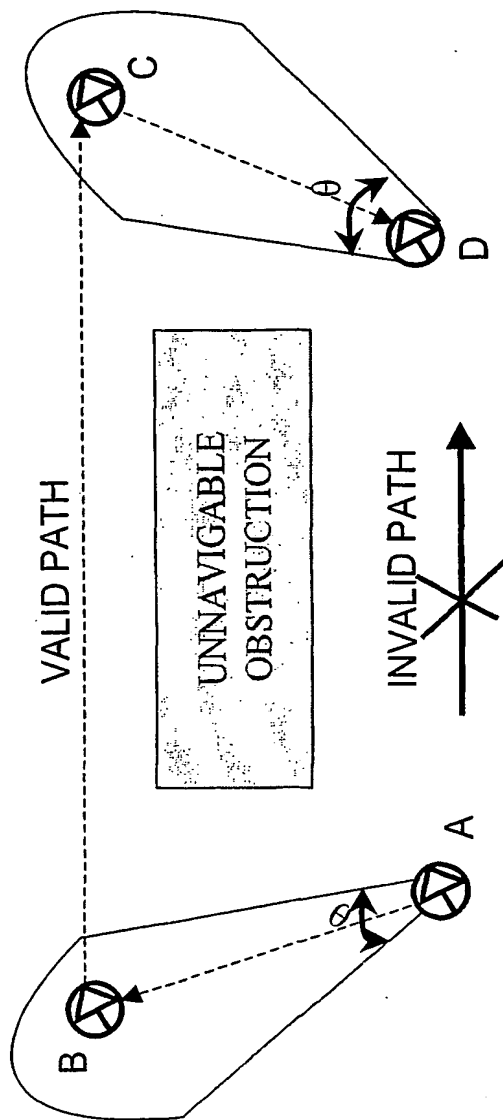
16/17

FIGURE 16A



NAVIGATIONAL NODE WITH VALID
LOS CONSTRAINED TO A RANGE 0°
TO θ°

FIGURE 16B



17/17

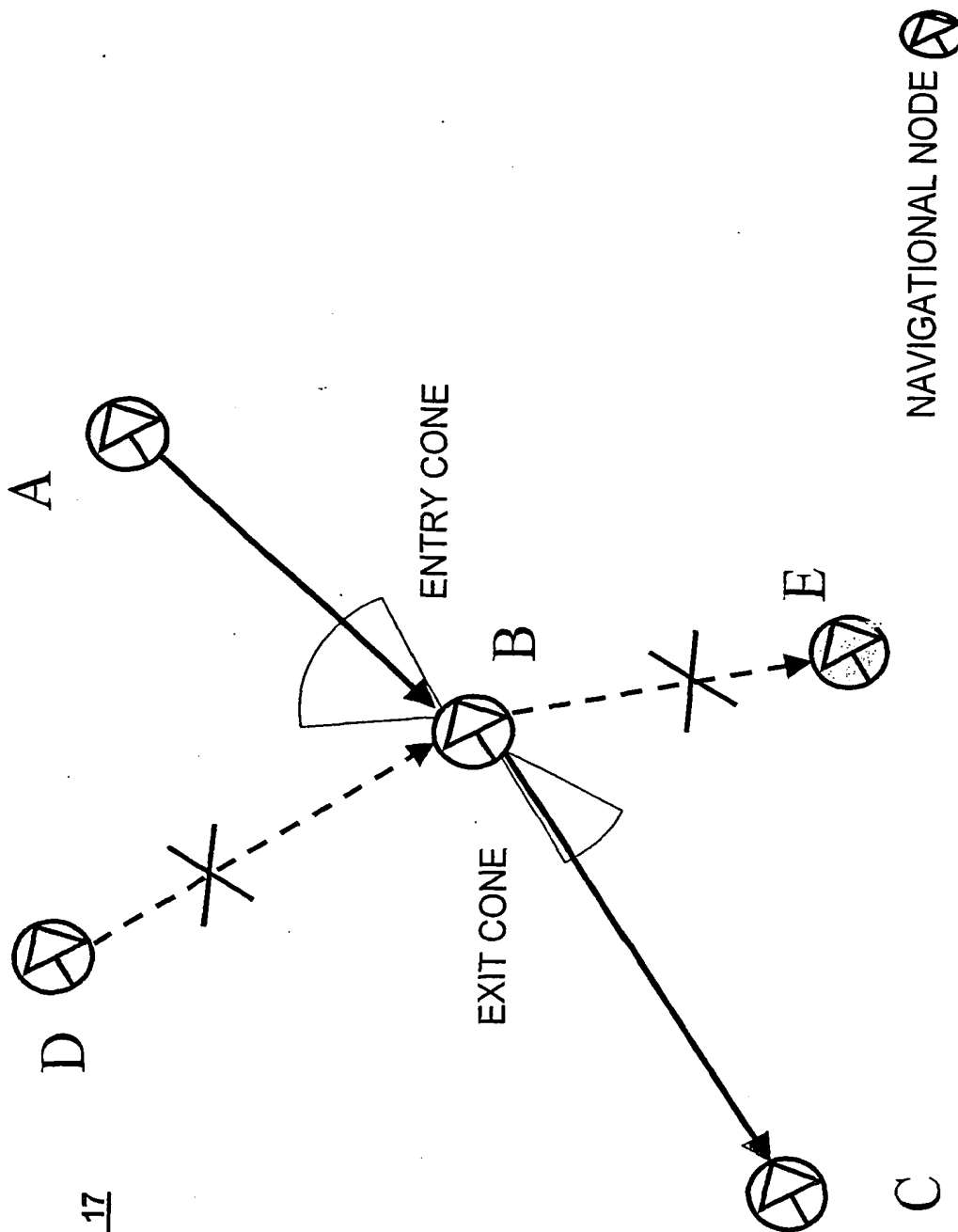


Figure 17